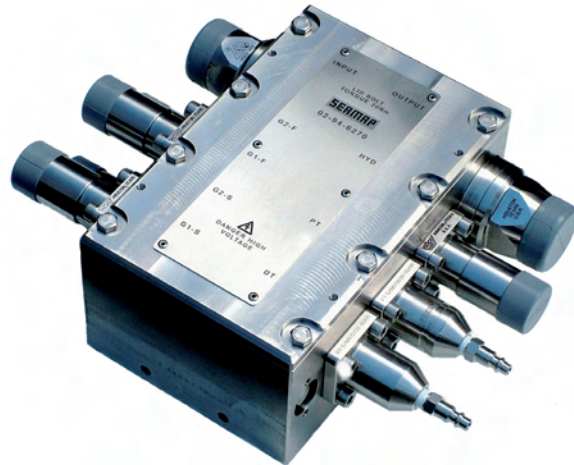




## GunLink 4000 | Fully Distributed In-Water Hydrophone Data Acquisition and Gun Controller

- **Gun Capacity:** Firing and Sensor Circuits for up to 256 guns (128 GI Guns).
- **Near Field Phone Monitoring:** Up to 512 near field phone 24 bit inputs sampled continuously at 0.1mS.
- **Depth and High Pressure Inputs:** Each Gun Firing Sensing Module is fitted with a depth and a high pressure air sensor.
- **User Interface:** Twin screen Graphical User Interface.
- **MOB Interface:** Direct interface to vessel's Seamap MOB system.
- **Air System:** To simplify the air distribution at the cluster.
- **Media Converters:** Removes the requirement for fibre optic slip-rings.
- **Umbilical Termination:** Provides power connections for additional in water auxiliary equipment such as the BuoyLink EX GPS Tracking System.



### The GunLink 4000 is the third phase of Seamap's range of new generation hydrophone monitoring and gun control systems.

The system provides in-water firing control and sensor timing monitoring of up to 256 standard guns (128 GI guns) and is capable of receiving hydrophone data from up to 512 near field phones. The GunLink 4000 moves the system electronics in to the water allowing it to be mounted close to the gun array, thus reducing umbilical diameters, increasing umbilical lengths and allowing shorter offsets.

The GunLink 4000 comprises of a Host Computer and Timing Control Unit (TCU), an Umbilical Termination Module (UTM) for each umbilical and a Gun Firing & Sensing Module (GFSM) for each one or two gun cluster. The GFSM also incorporates a depth sensor, a pressure sensor and an internal hydrophone or a connector for an external hydrophone. The GFSM is available in two configurations, the first for the Bolt Technologies Annular Port Gun (APG) and the second for a conventional gun hanging plate installation. The GFSM's

are daisy chained along the array starting from the UTM with only a single cable between each module thus reducing the complexity of the array wiring.

Individual gun fire times and solenoid coil current logging enables the firing pulse to be fed to each gun solenoid at the calculated time for a programmable period and voltage. The in-water circuitry allows each near field phone and firing sensor to be monitored continuously using a 24 bit A/D converter sampling at 0.1mS thus providing increased gun firing accuracy and auto-fire detection. The Host Computer runs the main operating and control software under the LINUX operating system and provides the main system control and display functions. The software has been designed to be both intuitive and simple to use, providing the operator with real time data and easily recognizable indications of deteriorating gun performance.

# GunLink 4000

## Specifications

|   |   |
|---|---|
| <b>General System Features</b>                          |   |
| <b>Total Number of Guns</b>                             | 256 (128 GI Guns)   |
| <b>Monitored Variables</b>                              | Gun fire time<br>Near field phone signals (Optionally up to 2 per gun)<br>Depth sensor and air line pressure (Up to one of each per gun plate)<br>Solenoid coil current |
| <b>Controlled Variables</b>                             | Gun fire time<br>Gun firing pulse length and voltage  |
| <b>Ancillary Monitored Variables</b>                    | Atmospheric pressure<br>Up to 23 compressor and umbilical line pressure inputs  |
| <b>Remote Displays</b>                                  | Large format digital pressure displays to display umbilical pressures on the gun deck.  |
| <b>Supported Guns</b>                                   | Bolt 1500 and 1900 and APG<br>I/O Sleeve Gun<br>G and GI Gun  |
| <b>Safety Features</b>                                  | Key controlled remote and local system disable<br>Bleed resistors on each solenoid output dump charge at system disable<br>Interface to vessel's MOB system             |
| <b>System Performance</b>                               |   |
| <b>Timing Resolution</b>                                | 0.1 mS.   |
| <b>Fire Detect Window</b>                               | 120 mS.   |
| <b>Synchronization Modes</b>                            | Automatic (Additional algorithms available as required)   |
| <b>Fire Detect Method</b>                               | Sensor or Hydrophone selectable   |
| <b>Fire Time Pick Method</b>                            | Zero crossing, level detect, peak detect or combinations of all three   |
| <b>Data Time Stamping</b>                               | All data time stamped to GPS time   |
| <b>Software</b>   |   |
| <b>Graphical at-a glance status screen</b>              | Continuous update for each gun to indicate Gun fire; errors (faults); auto-fire; double pop; depth; pressures and timing performance for each gun                       |
| <b>Text Based status in tabular Format for Each Gun</b> | Physical addressing; volume; timing error value; gun fire delay value; aim point offset value; depth value; array assignment; operational status and fault indication   |
| <b>Input Power</b>                                      | 110 to 240 Volt AC, 50/60 Hz;   |
| <b>Dimensions</b>                                       | 19" Rack Mount in Instrument Room; TCU = 2U;  |



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